



Operating TAK over HF Radio

Isode

TAK is a widely used system for reporting location and status information. This white paper describes how to operate TAK efficiently over HF radio using open standards for all aspects of the communication.

What is TAK?



TAK stands for two things:

- Tactical Assault Kit. This reflects its initial military use by the Marine Corps. It is now used much more widely.
- Team Awareness Kit. This reflects wider use for Law Enforcement, First Responders, Commercial and recreational purposes.

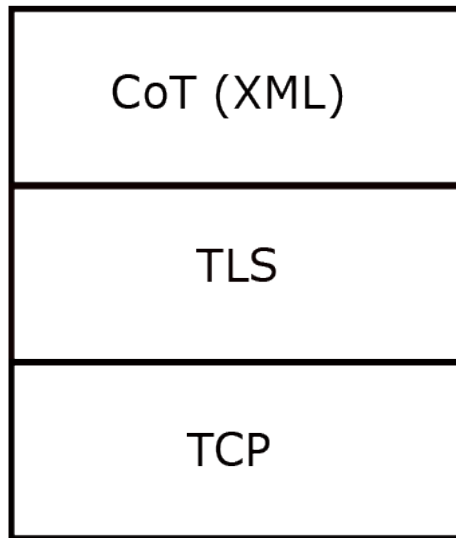
TAK is provided as a number of open-source client and server implementations. There is plenty of information on TAK generally available, which is not repeated here. The best place for information is <https://tak.gov/>, which also provides access to client and server implementations.

Client implementations provided for all major platforms:

- Android (ATAK) is downloadable from Google Play. This is the most widely used client, shown in the screenshot above.
- iPhone (iTAK) is available from the App Store.
- Windows (WinTAK) is available from tak.gov.

There are several TAK server implementations. The most widely deployed one and the one described in this paper is the open-source server developed by Raytheon and available from tak.gov.

TAK Protocols and Deployment with TAK Servers



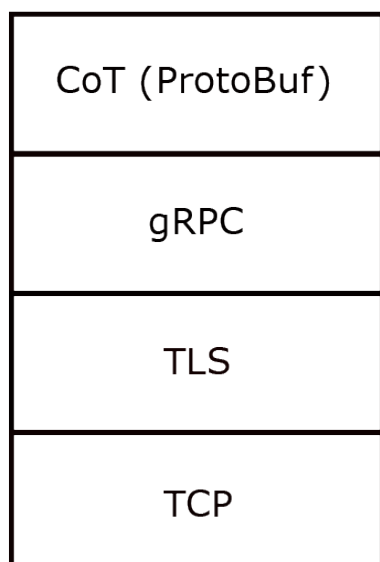
TAK uses the protocol stack shown above for Client-to-Server communication. The TLS (Transport Layer Security) provides link security.

CoT (Cursor on Target) is an XML format designed by Mitre Corporation to handle a range of message types. When used in TAK, the encoding is specified by the initial byte. TAK clients generally use an XML encoding.

While the XML encoding is widely supported, current systems will generally use a more compact Protobuf encoding.

The TCP/TLS connection is opened using two-way strong authentication. Then a stream of CoT messages flows in both directions.

There is also a mapping onto UDP (User Datagram Protocol), which is discussed in the Serverless TAK section.



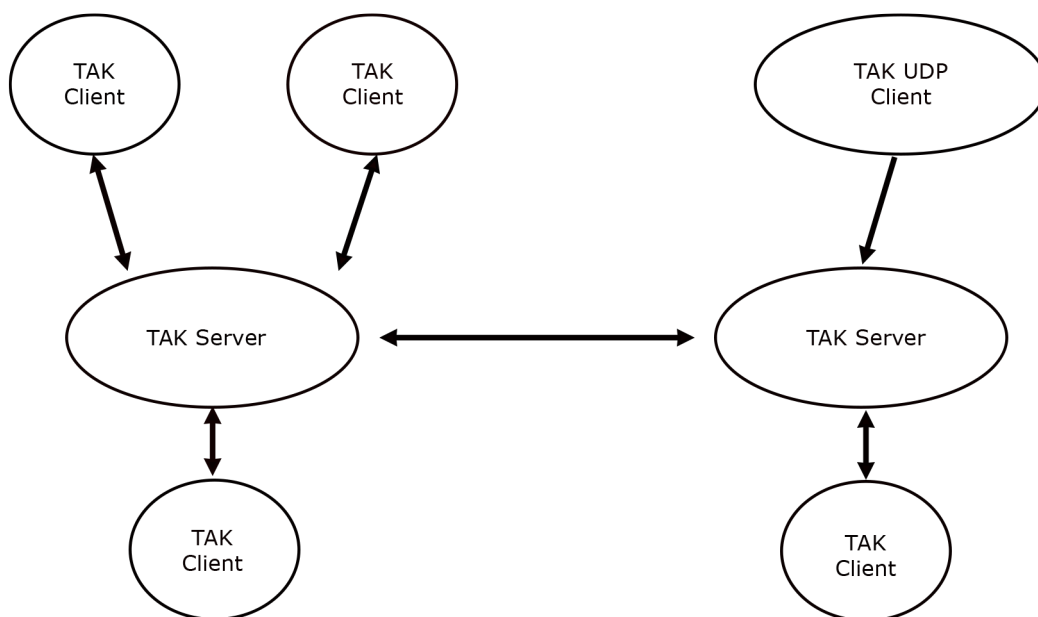
TAK uses the protocol stack shown above for server-to-server communication. Key differences with the Client to Server protocol:

CoT messages use a protoBuf encoding, which is more compact than XML.

There is a gRPC layer added, which provides message framing and keepalive heartbeats using HTTP/2.

TAK servers can federate with other servers and are typically configured to filter traffic that is appropriate for each peer server. It is also possible to use a special federation server that interconnects a number of TAK servers with a "star" configuration.

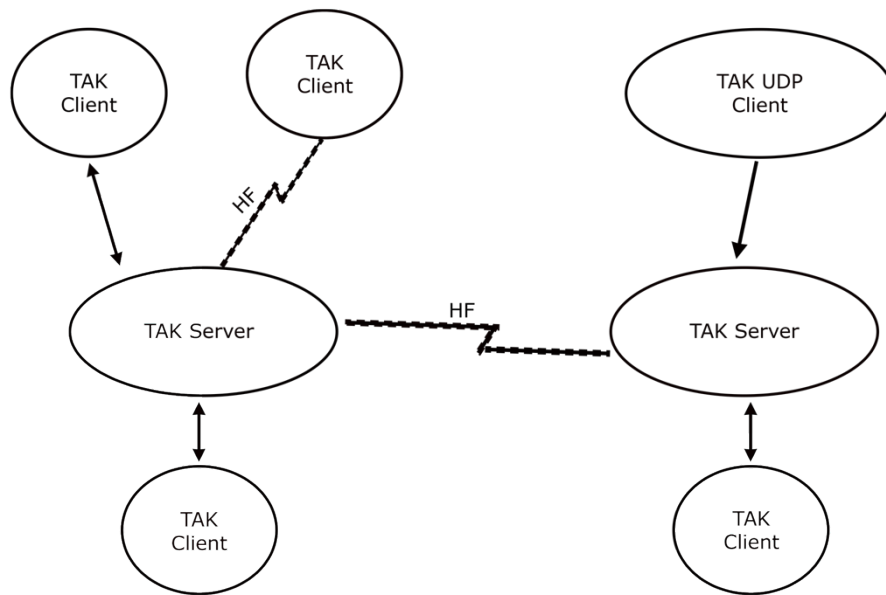
The following diagram shows a simple TAK configuration



TAK messages flow between clients and servers, noting that for TAK, UDP clients only send messages. Messages may be sent from one client to a single client. More commonly, messages are sent to groups of clients to widely share location and other information.

Operation over HF

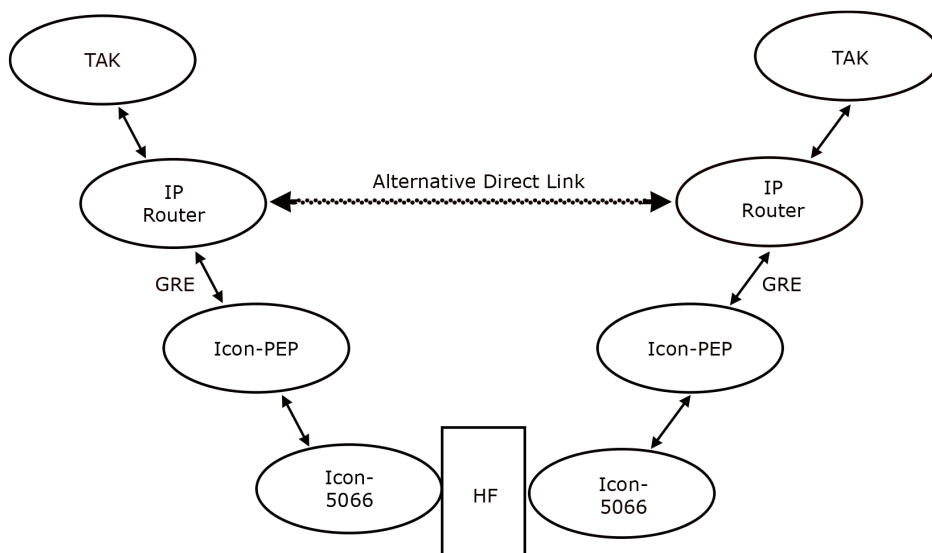
The links shown above will operate over IP networks. The solution described here enables one or more of these links to operate over HF using an approach which is transparent to TAK clients and servers. The following diagram shows where this can be provided.



There are two potential places where HF can be used in the TAK architecture, illustrated above:

1. Between a pair of TAK servers. Two example scenarios:
 1. To connect TAK servers on two ships using an HF link.
 2. To connect a field HQ to base, with field clients accessing the server over both UDP and TCP. This can include nodes simply using TAK or CoT to report position.
2. Between a TAK client and server. For example, a mobile TAK client might connect to its server using HF.

The technical solution described next can be applied to either of these scenarios.



The diagram above shows the architecture using the Isode products that support it. This approach uses open standards, so equivalent products could be used. This enables two TAK servers to communicate over HF.

The bottom layer shows Icon-5066, which uses STANAG 5066 as the link layer over HF. This is described in the Isode white paper [STANAG 5066: The Standard for Data Applications over HF Radio](#). Use of STANAG 5066 is important to provide reliability and to enable multiple applications to share the underlying HF infrastructure.

Icon-PEP is an application running over STANAG 5066 that provides a TCP PEP, as described in the Isode white paper [Providing TCP Services over HF Radio](#). The TCP connection from the TAK server or client is terminated at Icon-PEP, and the Icon-PEP servers communicate over HF with the optimized HF-PEP protocol specified in STANAG 5066 Annex X (Ed5 draft). HF-PEP provides:

1. Very efficient use of the underlying STANAG 5066 service.
2. Compression, which is very effective for TAK where messages share common elements.

Isode's Icon-PEP includes two things which are critical for TAK operation over HF:

1. TLS Proxy. This means that TLS is not used directly over HF. This avoids the overheads and handshaking of TLS and enables compression of stream data. Details in the Isode white paper, [Providing TCP Services over HF Radio](#).
2. HTTP/2 proxy. This enables the TAK S2S protocol to operate efficiently over HF. This proxy handles HTTP/2 heartbeats locally and extends HTTP/2 window size.

A TAK server or client will communicate indirectly with Icon-PEP through an IP router, which will connect to Icon-PEP using GRE (Generic Routing Encapsulation), which is supported by most suitable IP routers. The IP router essentially treats Icon-PEP as an adjacent IP router.

A key benefit of the IP router architecture is that the IP router can be aware of IP routes to the peer. This enables the use of direct IP links when available, with switching to HF when they are not. This is important, as HF will invariably provide a poorer link to direct IP and should only be used when it is the only option.

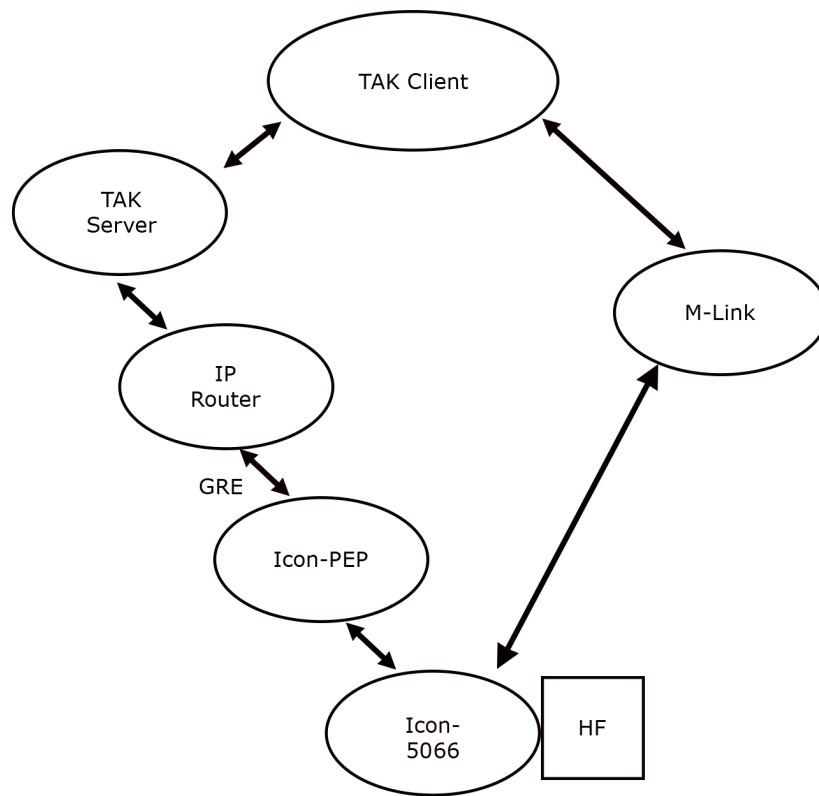
Chat and XMPP

Chat is an increasingly important capability. TAK clients offer two chat capabilities:

1. Chat using CoT can be used to communicate with other members of a TAK network.
2. Chat using XMPP, which enables communication with a wider set of users.

The built-in chat is supported as part of the core TAK system. XMPP needs additional components to work over HF. A detailed description is provided in the Isode white paper [Operating XMPP over HF Radio and Constrained Networks](#). The summary is that this can

be supported by Isode’s M-Link server, which can communicate over STANAG 5066. This provides a good example of the benefits of using STANAG 5066 to multiplex applications.



It can be seen that a TAK client will talk to both a TAK server and an M-Link XMPP server. Both XMPP and TAK traffic is then multiplexed by Icon-5066 over HF.

Performance Measurements

Measurements were made in the lab using the Isode products Icon-PEP and Icon-5066 as illustrated above, with a simulated HF Network provided by Isode’s MoRaSky tool. Two configurations were measured: client/server and server/server.

Speeds for each test: 9600 bps, which is the top speed of narrowband HF, 1200 bps, and 75 bps. All using a short interleaver.

Latency tests were made by measuring the latency between two WinTAK clients for an object location message. The typical size of the CoT XML messages is a few hundred bytes. Latency was measured by sending messages and manually timing.

Traffic was generated using the PyTAK Python TAK library. Measurements were made using standard CoT messages reporting the location of an object. Here is an example:

```

<?xml version="1.0" encoding="UTF-8"?>
<event version="2.0" type="a-f-G-U-C-I" uid= 8fea07f0-c92e-d96b-fbb8-7e3d589203f2" how="m-g"
time="2025-04-30T12:22:24Z" start="2025-04-30T12:22:24.894060Z"
stale="2025-04-30T12:23:24.894068Z">
<point lat="51.4148" lon="-0.3621" hae="0" ce="10" le="10" />
  
```

```

<detail>
  <contact callsign="PYTHON2" endpoint="*:-1:stcp" />
  <__group name="Cyan" role="Team Member" />
  <sequence position="1" total= 3000" />
  <_flow-tags_ TAK-Server-050b185011374f1e8e841f6ced9cb961="2025-04
30T12:22:24Z />
</detail>
</event>

```

This is a standard object message, extended sequence and position to facilitate monitoring. The time was current when sent, and the location was generated randomly. On average, messages were 530 bytes.

Client/Server

In this setup, the Icon-PEP chains were inserted between WinTAK clients and the TAK server. The WinTAK connection monitoring was turned off. This WinTAK option generates traffic that makes HF operation not viable.

Speed	Latency
9600 bps	8 secs
1200 bps	5 secs
75 bps	29 secs

At 75 bps, the latency is mostly due to the time it takes to transfer the data. The latency at the higher speeds is dominated by HF turnaround times. The HF link is handshaking back and forth, so the exact transfer time varies, depending on when in the cycle the message is sent.

For 1200 bps with a short interleaver, the block size is 90 bytes (0.6 secs), leading to a handshake cycle time of around 4 seconds. For 9600 bps, with a short interleaver block size is 1292 bytes (1.08 seconds), leading to a handshake cycle time of around 7.6 seconds.

Faster turnaround time at 9600 bps could be achieved by using a very short or ultra-short interleaver. There is a tradeoff here, as a longer interleaver increases reliability.

Throughput measurements are shown in the following table.

Speed	Throughput	Effective Speed	Compression
Direct	588 msg/min	41,552 bps	n/a
9600 bps	540 msg/min	38,160 bps	91%
1200 bps	313 msg/min	22,118 bps	95%
75 bps	5.8 msg/min	410 bps	90%

The direct connection over a fast link effectively shows the performance limitations of the TAK servers. Performance at 9600 bps was limited by this, whereas at 1200 and 75 bps, performance is limited by the link.

Server / Server

This test was made between two standard TAK servers, using the built-in client. Icon-PEP was configured as a TLS proxy with HTTP/2 proxy enabled.

Speed	Latency
9600 bps	10 secs
1200 bps	6 secs
75bps	33 secs

These numbers are similar to the client/server numbers but slightly higher. The client/server analysis applies.

The message size for server-to-server communication using gRPC is 376-380 bytes, which is somewhat smaller than the XML Client/Server (530 bytes). In the table below, effective speed is calculated based on the XML message size

Speed	Throughput	Effective Speed	Compression
Direct	593 msg/min	41,905 bps	n/a
9600 bps	586 msg/min	41,410 bps	88%
1200 bps	352 msg/min	24,874 bps	95%
75 bps	5.9 msg/min	416 bps	87%

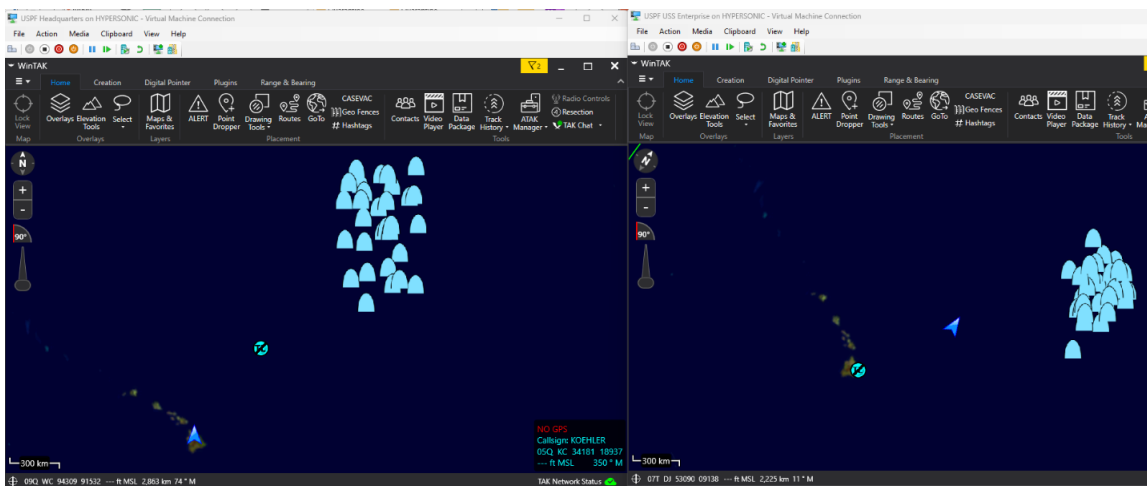
The direct connection over a fast link effectively shows the performance limitations of the TAK servers. Performance at 9600 bps was limited by this, whereas at 1200 and 75 bps, performance is limited by the link. Throughput is very similar to client/server.

Congestion Control

TAK Server to Server protocol support in Icon-PEP provides congestion control. This provides two basic functions to optimize performance:

1. Deletion of very old messages, on the basis that they are no longer relevant. It is anticipated that this will only be needed when HF fails to connect for an extended period.
2. For Tracks, which report entity location and are typically updated frequently, if an update arrives while an earlier track is queued, the track will be updated with the latest one. This enables tracks for many entities to be handled over a slow HF Link.

Congestion control is covered in detail in the Isode white paper "[Congestion Control for C2 over HF Radio](#)"

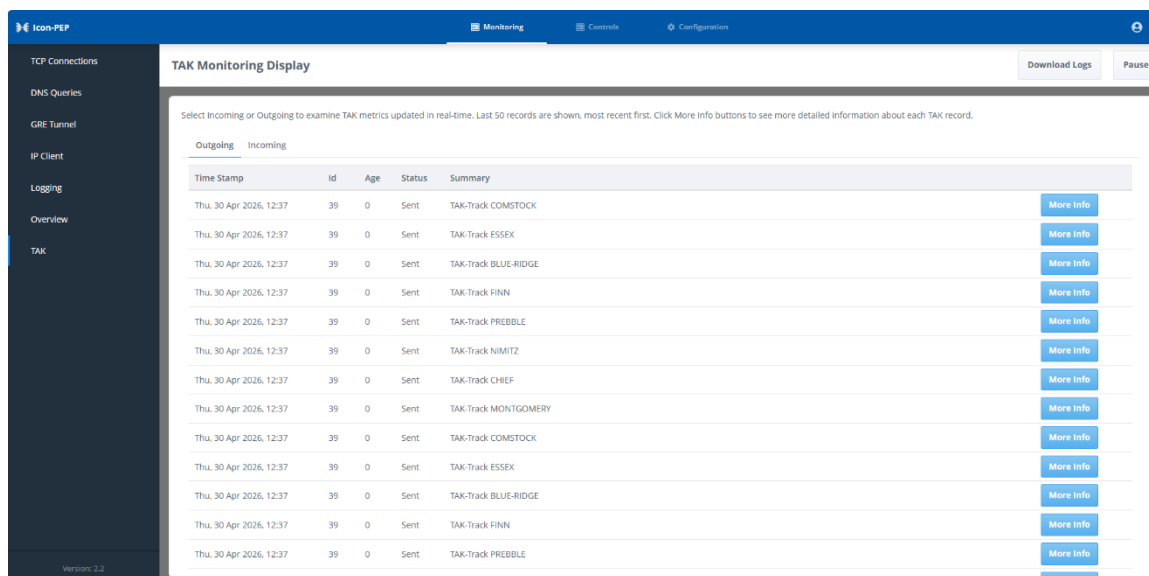


The above screenshot shows two WinTAK clients connected over a simulated HF link. Tracks are being generated on the LH system. The RH system has the tracks sent over HF with the display following changes on LH. This demonstration shows maintaining Tracks for 30 objects over an HF link at 600 bps.

The result is that the system “keeps up” and the techniques described prevent congestion build-up and enable the connected system to show information that is close to current.

Monitoring

The approach for congestion control means that each TAK PDU is handled separately and interpreted. This enables Icon-PEP to provide effective monitoring of a TAK stream, so that the operator can see the flow of TAK messages, as shown below.



There is also an option for the operator to view the detailed structure of each TAK message.

TAK Detail - Id #30

Time Stamp: Thu, 30 Apr 2026, 12:33

Message: TakQueue

Age: 0

Status: Sent

Record:

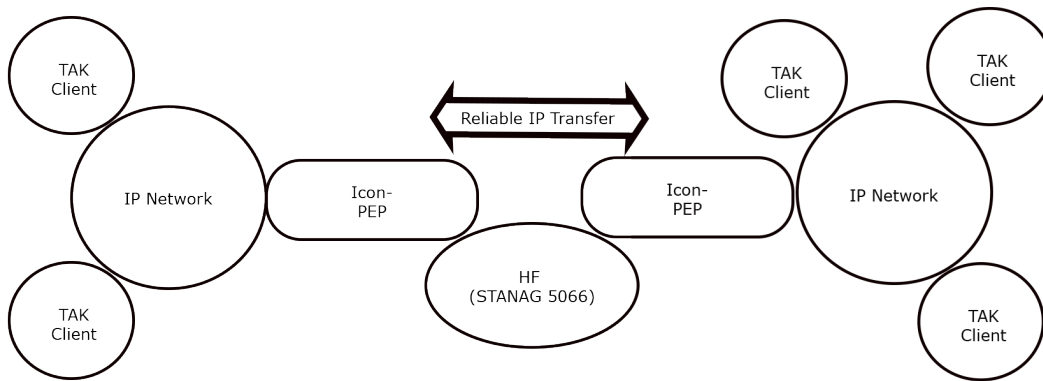
```
{
  "federate_groups": [
    "USPF-ENTERPRISE",
    "USPF-HQ"
  ],
  "federate_provenance": [
    {
      "federation_server_id": "8fa1a2cd7d774a13b35b47f996feac1a"
    }
  ],
  "federate_hops": {
    "max_hops": -1,
    "current_hops": 1
  }
}
```

Serverless TAK

The paper has so far considered TAK using TAK server. TAK can also be used without a server, making use of IP Multicast and each XML TAK message sent in a UDP datagram over IP. This mode is useful in a range of tactical scenarios.

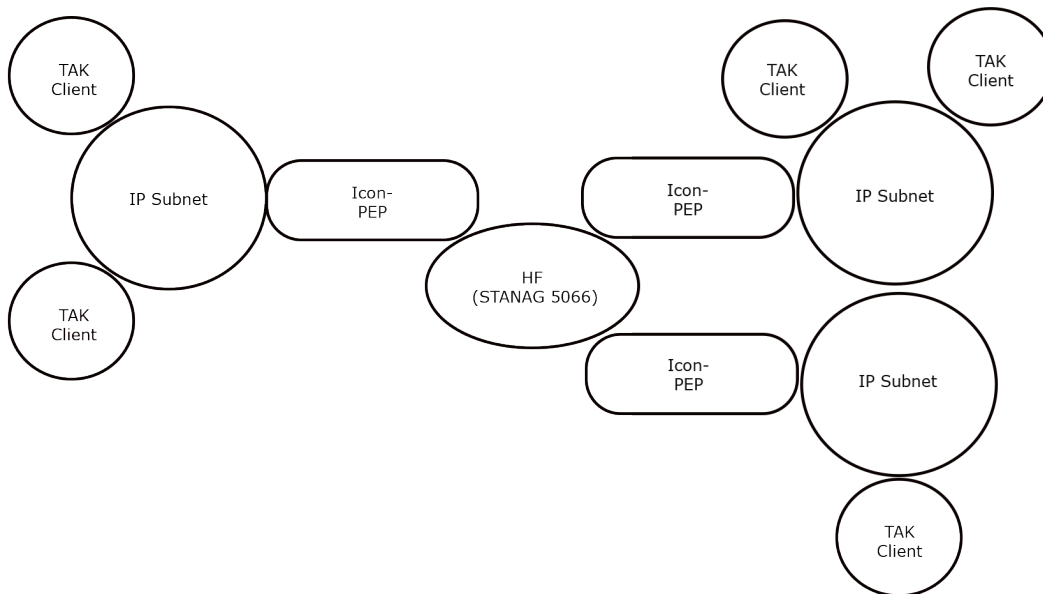
Icon-PEP provides an option to support multicast IP over HF, described in the Isode white paper "[IP Multicast over HF Radio](#)".

This can be used in two ways. The first method is to connect two TAK multicast networks using a reliable (ARQ) link, shown in the following diagram.



This approach leads to a robust interconnection of two TAK multicast networks over HF.

The second approach, shown below, supports the interconnection of multiple TAK multicast networks using HF broadcast.



There are two variants of this architecture:

1. True multicast, with all clients able to transmit. This will be connected using STANAG 5066 MAC layer with CSMA (STANAG 5066 Annex K) or Wireless Token Ring Protocol (WTRP). The MAC layer will allow each node to transmit as needed.
2. The second is broadcast, where one node operates as broadcast sender and all other nodes as broadcast receivers. This supports a model where messages are broadcast without break to any listening nodes.

The choice of model will depend on the deployed architecture.

Conclusions

This paper has shown how TAK can be deployed over HF using STANAG 5066 to enable link sharing. Measurements for Client/Server and Server/Server show that acceptable performance over HF can be achieved, and communication can work down to the lowest HF speeds. It describes the use of TAK with servers and without.

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